

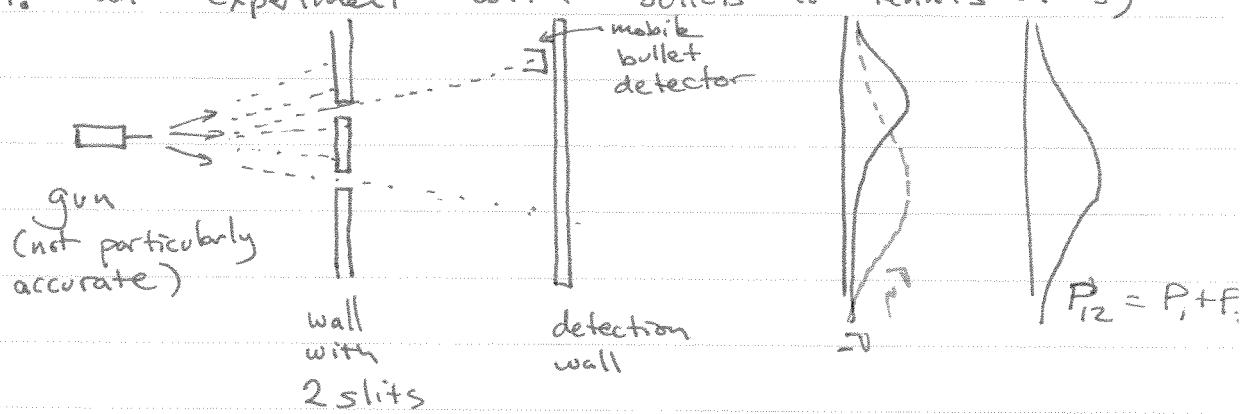
What is Quantum Mechanics?

1. The most successful (yet!) scientific description of how matter & energy interact on an atomic scale. This makes it the foundation of modern chemistry.
2. A frustrating mix of thought experiments, postulates, methods, and bizarre conclusions. "If you think you understand Quantum Mechanics, you probably don't."

Let's start with the essential Quantum Paradox:

2-slit experiments

1. an experiment with bullets (or tennis balls)

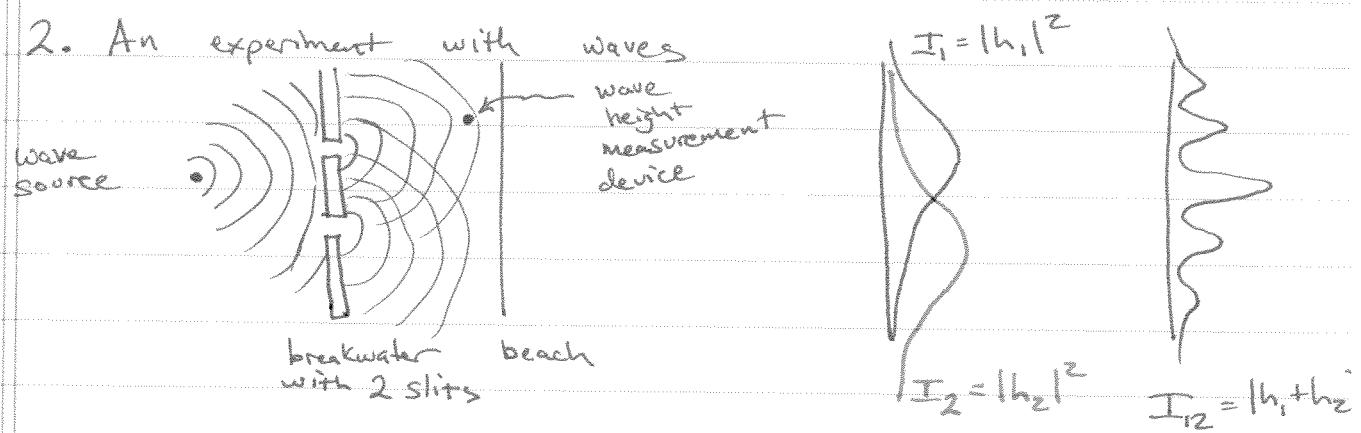


- The detector can be "counted" i.e. we can stop the experiment and count the number of bullets in the detector.
- A bullet may "bounce" off the edge of a slit and go anywhere.
- The amount of time the detector spends at each location is the same.

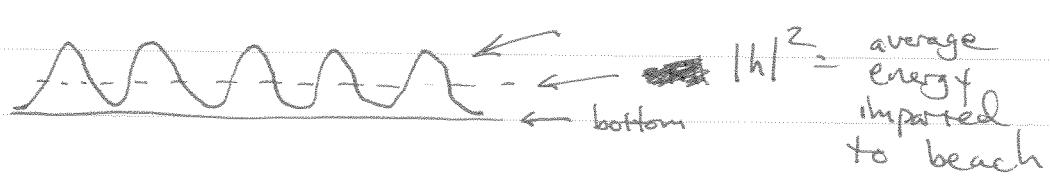
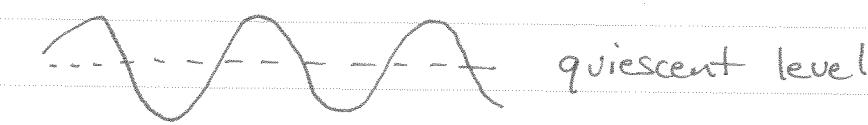
- Bullets arrive one at a time, but after a very long experiment, we obtain a distribution of bullets that came through each slit.
- The distribution when both slits are open is P_{12} . This is the sum of the distributions we get when only 1 slit is open.

$$P_{12} = P_1 + P_2$$

2. An experiment with waves

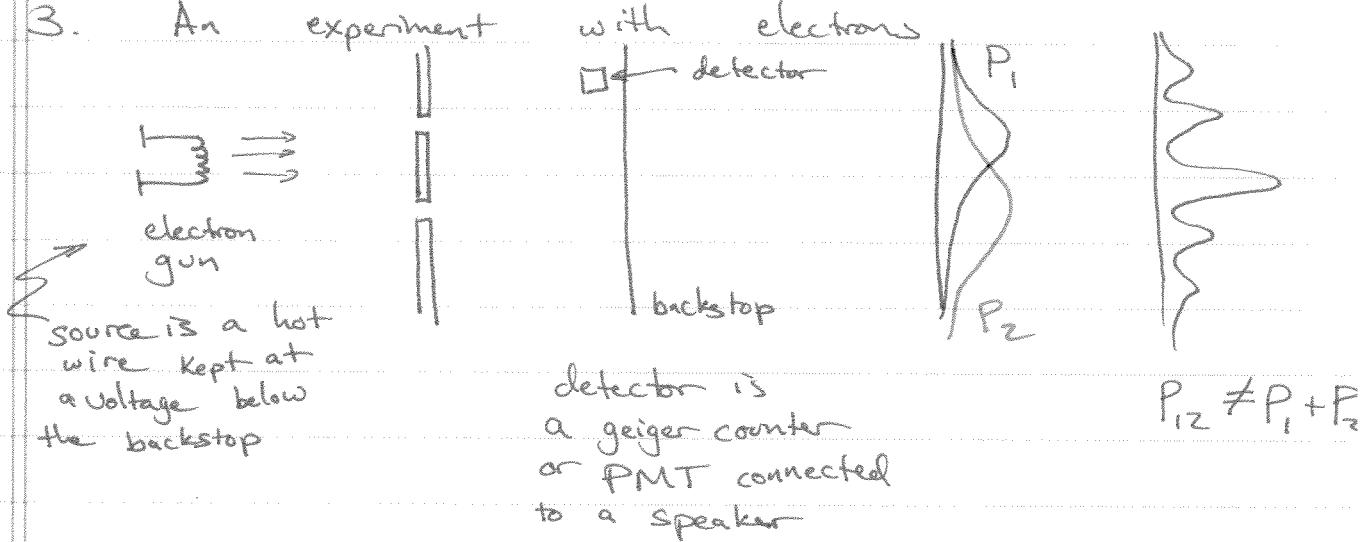


- Water waves are generated by a buoy that has a motor driving it up and down so that it makes circular waves
- The detector measures the intensity = $(\text{height})^2$ of waves that impinge on the beach



- An interference pattern develops because the 2 slits cause new circular wave patterns to form

3. An experiment with electrons



- There are no "partial" electrons. They arrive as particles (just like bullets). We can verify this with multiple detectors and very low discharge rates.

- When we move the detector, we can measure the intensity at a location from the average number of clicks/second: More electrons = more clicks

Proposition: Let's say that each electron goes through either hole 1 or hole 2.

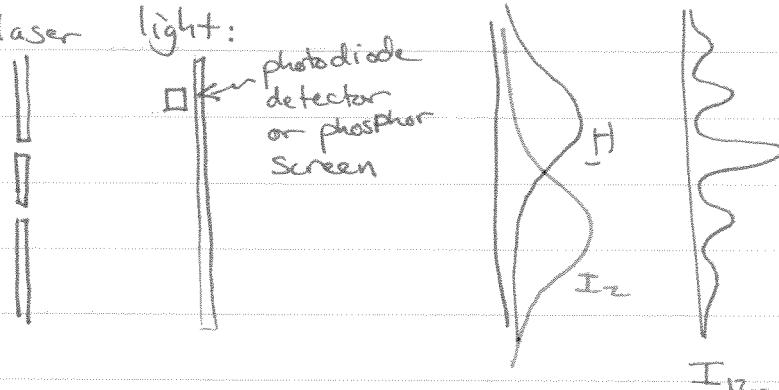
We can check this by blocking hole 1 and hole 2 (one at a time), then do the experiment again with both open. The proposition would require $P_{12} = P_1 + P_2$

So electrons are going through both slits simultaneously and collapsing to a single position as they hit the detector.

4. An experiment with laser light:

laser 

(narrow beam at
a single frequency)



What will happen if we lower the fluence of the laser so much that only a few photons are hitting the slits each second?

Do we get individual particle-like clicks at the detector?

Math Review

- You should know basic integration & differentiation
- I'll teach you some of the other techniques we'll use: (Differential Equations, Linear Algebra, Integration tricks)

Quantum Mechanics uses complex numbers which have both real & imaginary parts:

$$z = a + bi$$

$\xrightarrow{\text{Complex}}$ $\xrightarrow{\text{real}}$ $\xrightarrow{\text{Imaginary}}$

$$i = \sqrt{-1} \Rightarrow i^2 = -1$$

These numbers come about naturally from the roots of quadratic equations:

$$z^2 - 2z + 5 = 0$$

$$z = \frac{2 \pm \sqrt{4 - 20}}{2} = 1 \pm \sqrt{-4}$$

$$z = 1 \pm 2i$$

$$\text{For this particular number: } \operatorname{Re}[z] = 1$$

$$\operatorname{Im}[z] = \pm 2$$

$$\text{In general if } z = a + bi \rightarrow \begin{cases} \operatorname{Re}[z] = a \\ \operatorname{Im}[z] = b \end{cases}$$

Complex Numbers have a complex conjugate, denoted with an asterisk:

$$z = a + bi \quad z^* = a - bi$$

Complex Numbers also have a norm:

$$|z| = \sqrt{|z|^2} \quad \text{where} \quad |z|^2 = z \times z^*$$

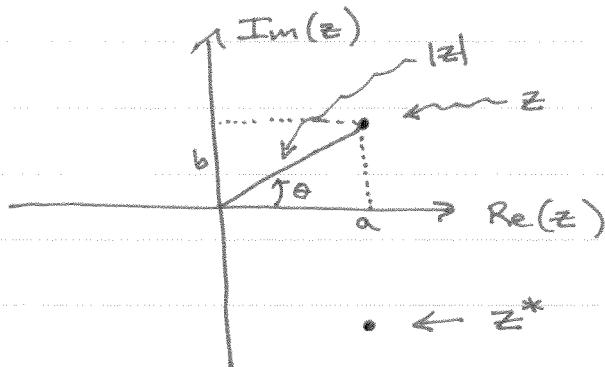
$$= (a+bi)(a-bi)$$

$$= a^2 - bai + abi - b^2i^2$$

$$|z|^2 = a^2 + b^2$$

So, $|z| = \sqrt{a^2 + b^2}$

Another way to think about complex numbers involves a plane where 1 axis is the real axis and the other is the imaginary axis:



Instead of x- and y-coordinates, we could also use radial coordinates

$$z = |z| \cos \theta + i |z| \sin \theta$$

a b

$$z = |z| e^{i\theta}$$

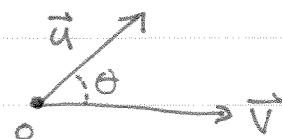
↑ magnitude ↑ phase

To do this last step, we have used Euler's relation:

$$e^{i\theta} = \cos \theta + i \sin \theta$$

(What is $e^{-i\pi}$?)

Vectors



$$\vec{u} = \begin{pmatrix} u_x \\ u_y \\ u_z \end{pmatrix}$$

$$\vec{v} = \begin{pmatrix} v_x \\ v_y \\ v_z \end{pmatrix}$$

Two vectors in 3-D space

Each has 3 components describing a direction in space or a displacement from some origin O

The scalar or inner product of 2 vectors:

$$\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos\theta$$

$$= u_x v_x + u_y v_y + u_z v_z$$

The length of a vector:

$$|\vec{u}| = \sqrt{\vec{u} \cdot \vec{u}} = \sqrt{u_x^2 + u_y^2 + u_z^2}$$

It looks a lot like the magnitude of a complex number...

Unitvectors have a length of 1:

$$|\vec{u}| = 1$$

these vectors are said to be normalized.

Orthogonal vectors: $\vec{u} \cdot \vec{v} = 0$

$$= |\vec{u}| |\vec{v}| \cos\theta$$

It implies $\theta = \frac{\pi}{2}$

Orthonormal vectors:

$$\vec{u} \cdot \vec{v} = 0$$

$$\vec{u} \cdot \vec{u} = 1$$

$$\vec{v} \cdot \vec{v} = 1$$

Partial Derivatives. Suppose we have a function of 2 variables, $f(x, y)$

$\frac{\partial f}{\partial x}$ = Hold y constant and take a derivative with respect to x

$\frac{\partial f}{\partial y}$ = Hold x constant & take a derivative wrt y

Here's an example:

$$f(x, y) = x^2 + 2xy^2 - y^3$$

$$\frac{\partial f}{\partial x} = 2x + 2y^2$$

$$\frac{\partial f}{\partial y} = 4xy - 3y^2$$

Operators:

Does something to a function, number, or vector

Examples:

$2x$, $\sqrt{\cdot}$, $\frac{\partial}{\partial x}$, inversion, rotation

The ordering of operators is important because if we reverse the order, we don't always get the same results!

two operators (with hats) $\hat{O} = \frac{\partial}{\partial x}$ $\hat{P} = x$

Suppose we have a function $f(x,y) = x^2 + y^2 + 2x^4y$

$$\begin{aligned}\hat{O}\hat{P}f &= \hat{O}[x^3 + xy^2 + 2x^5y] \\ &= 3x^2 + y^2 + 10x^4y\end{aligned}$$

$$\begin{aligned}\hat{P}\hat{O}f &= \hat{P}[2x + 8x^3y] \\ &= 2x^2 + 8x^4y\end{aligned}$$

The commutator $[\hat{O}, \hat{P}] = \hat{O}\hat{P} - \hat{P}\hat{O}$

If $[\hat{O}, \hat{P}] = 0$ for all functions f , then we can say that operators \hat{O} & \hat{P} commute.

Linear operators have 2 important properties:

1) $\hat{P}(f+g) = \hat{P}f + \hat{P}g$

2) $\hat{P}(af) = a\hat{P}f$
↑ ↑
scalar function

$\frac{\partial}{\partial x}$ is a linear operator, $\sqrt{\cdot}$ is not

Rotation operators

$$R_{xy}^\phi = \begin{pmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

rotate by an angle ϕ
in the x, y plane

Rotation operators are matrices that operate on vectors:

$$\begin{aligned} \vec{u}' &= R_{xy}^\phi \vec{u} && \text{for original vector} \\ &= \begin{pmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} u_x \\ u_y \\ u_z \end{pmatrix} \\ &= \begin{pmatrix} u_x \cos\phi + u_y \sin\phi \\ -u_x \sin\phi + u_y \cos\phi \\ u_z \end{pmatrix} && \leftarrow \text{rotated vector!} \end{aligned}$$

Eigenvalue equations

$$\hat{P} f = P_f f \quad \begin{matrix} \text{on the same function as on} \\ \text{the left hand side!} \end{matrix}$$

\hat{P} operator f function P_f eigenvalue
 for function f

example:

$$\hat{P} = \frac{\partial^2}{\partial x^2} \quad f = \sin ax$$

$$\hat{P}f = -a^2 \sin ax = -a^2 f$$

- $\sin(ax)$ is an eigenfunction of $\frac{\partial^2}{\partial x^2}$ with eigenvalue $-a^2$
- $\cos(ax)$ is also an eigenfunction of $\frac{\partial^2}{\partial x^2}$, also with eigenvalue $-a^2$
- These are degenerate eigenfunctions (they share eigenvalues)

Question: What other functions are also eigenfunctions of this operator? Is it a linear operator?

Question: What if $\hat{P} = \frac{\partial}{\partial x}$

$$\hat{P} \sin(ax) = -a \cos(ax) \rightarrow \text{not an eigenfct.}$$

But if $f = e^{iax}$

$$\hat{P} f = ia e^{iax} \leftarrow \text{this is!}$$

Central Paradox of QM:

- small enough particles act like waves (e^-)
- wave-like phenomena sometimes act like particles (photons)
- particle-like behavior: $P_{12} = P_1 + P_2$ ← probabilistic add
- wave-like behavior: $I_{12} = |h_1 + h_2|^2$ ← waves add & square
(particles pick one path or another
waves interfere, so the intensity takes interference into account)

What do waves act like?

- Classical Wave Equation

.

Before we get there, however, some math review

Complex #s

Vectors

Orthonormality

Partial Derivatives

Operators

Linear operators

Eigenvalue equations

A 1-lecture review
of last semester

The Classical Wave Equation

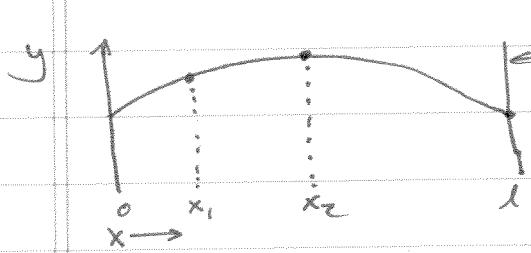
We'll be coming to the Schrödinger Equation soon, but here's a look at the time-dependent Schrödinger equation in 1-D:

$$i\hbar \frac{\partial}{\partial t} \psi(x, t) = \left[-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + V(x) \right] \psi(x, t)$$

On top of being an operator equation ($\frac{\partial}{\partial t}$, $\frac{\partial^2}{\partial x^2}$, and $V(x)$ are all operators), it is also a partial differential equation with a complex-valued function, $\psi(x, t)$.

It is also very similar to the classical wave equation, and much of quantum mechanics originates in the fundamental properties of wave motion.

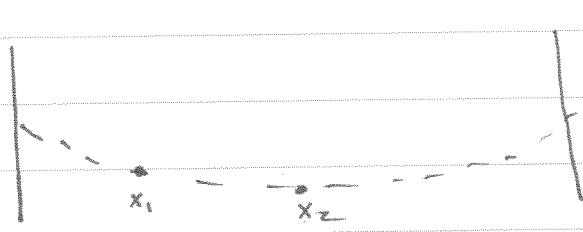
Consider a string stretched tightly between two walls:



At $t=0$

At any particular time, the y -positions of parts of the string at x, x_2 are not the same so $y=y(x)$ or y is a function of x .

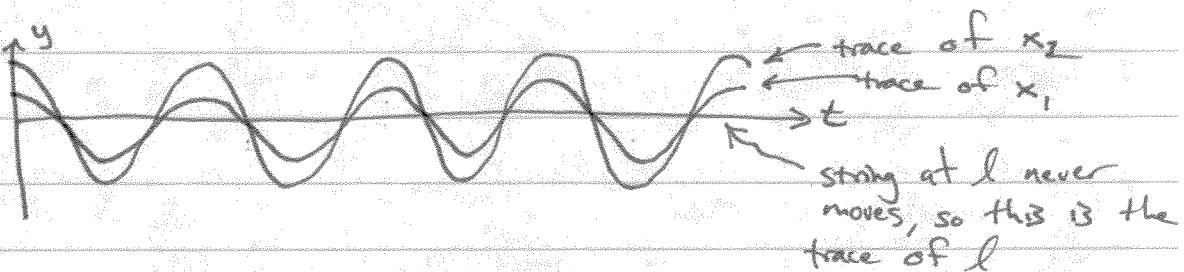
If we let the string go, what happens?



At $t=t'$

What we see now is that the y -positions at x_1 & x_2 are not fixed. They oscillate in time.

We can plot time traces of these special points:



So: $y = y(x, t) \longleftrightarrow y$ is a function of both x & t

The Classical Wave Equation (or CWE) shows us how these behave.

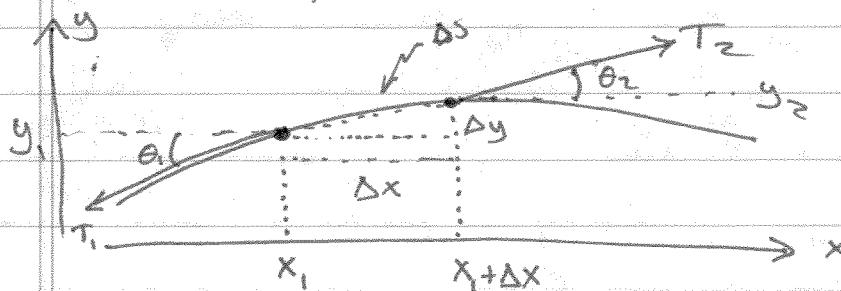
How will this string (non-moving at $t=0$) behave?



What about this one? →



Derivation of the CWE



A section of string in the vicinity of points (x_1, y_1) and (x_2, y_2)

- Assumptions:
- 1) For the segment of string, the only forces are the 2 tensions T_1 & T_2 (no gravity)
 - 2) String density is the same everywhere.
 - 3) The string only moves vertically ← not required but simpler
 - 4) $\frac{\partial y}{\partial x}$ & $y(x, t)$ are small (string is nearly flat)

We'll use some old school physics, $F=ma$ which has been with us since 1687, to solve this.

First we need the mass of the string segment.

$$m = \rho \underbrace{\Delta s}_{\text{length of segment}}$$

$$= \rho \sqrt{(\Delta x)^2 + (\Delta y)^2} = \rho \Delta x \sqrt{1 + \left(\frac{\Delta y}{\Delta x}\right)^2}$$

Using assumption 4 (the string is nearly flat, $\frac{\Delta y}{\Delta x} \ll 1$, so)

$$m \approx \rho \Delta x$$

Now, on to the forces.

The horizontal components of T_1 & T_2 must be equal or the whole string would move left or right:

$$T_1 \cos \theta_1 = T_2 \cos \theta_2$$

Since the string is nearly flat, $\cos \theta_1 \approx \cos \theta_2 \approx 1$

So: * $T_1 \cos \theta_1 \approx T_2 \cos \theta_2 \approx T$ ← total tension on the string.

The interesting forces are the vertical components

$$-T_1 \sin \theta_1 \text{ at point 1}$$

$$T_2 \sin \theta_2 \text{ at point 2}$$

Total force on segment:

$$F = T_2 \sin \theta_2 - T_1 \sin \theta_1$$

A sneaky trick (multiply by 1 or $\frac{T}{T}$):

$$F = \frac{T}{T} T_2 \sin \theta_2 - \frac{T}{T} T_1 \sin \theta_1$$

Substitute from the * equation above:

$$F \approx \frac{T}{T_2 \cos \theta_2} T_2 \sin \theta_2 - \frac{T}{T_1 \cos \theta_1} T_1 \sin \theta_1$$

$$= T \tan \theta_2 - T \tan \theta_1$$

$F = T (\tan \theta_2 - \tan \theta_1)$

Now $\tan \theta_2$ is the slope of the string at $x + \Delta x$, so expressing this in different symbols:

$$F = T \left[\left(\frac{\partial y}{\partial x} \right)_{x+\Delta x} - \left(\frac{\partial y}{\partial x} \right)_x \right]$$

Newton's 2nd law tells us: $F = ma$

$$F = (\rho \Delta x) \underbrace{\frac{\partial^2 y}{\partial t^2}}_{\substack{\text{from} \\ \text{before}}} \quad \begin{matrix} \text{definition of vertical} \\ \text{acceleration of the} \\ \text{string} \end{matrix}$$

$$T \left[\left(\frac{\partial y}{\partial x} \right)_{x+\Delta x} - \left(\frac{\partial y}{\partial x} \right)_x \right] = \rho \Delta x \frac{\partial^2 y}{\partial t^2}$$

Let's do a simple re arrangement

$$\frac{\left[\left(\frac{\partial y}{\partial x} \right)_{x+\Delta x} - \left(\frac{\partial y}{\partial x} \right)_x \right]}{\Delta x} = \frac{\rho}{T} \frac{\partial^2 y}{\partial t^2}$$

Now, if we take a limit as the segment gets very small, $\Delta x \rightarrow 0$, we recognize the left hand side as a second derivative

$$\lim_{\Delta x \rightarrow 0} \frac{\left[\left(\frac{\partial y}{\partial x} \right)_{x+\Delta x} - \left(\frac{\partial y}{\partial x} \right)_x \right]}{\Delta x} \rightarrow \frac{\partial^2 y}{\partial x^2}$$

So:

$$\frac{\partial^2 y}{\partial x^2} = \frac{\rho}{T} \frac{\partial^2 y}{\partial t^2}$$

We normally see this written in terms of the velocity of a wave in a string: $v = \sqrt{\frac{\rho}{T}}$

$$\frac{\partial^2 y(x,t)}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 y(x,t)}{\partial t^2}$$

← CWE!

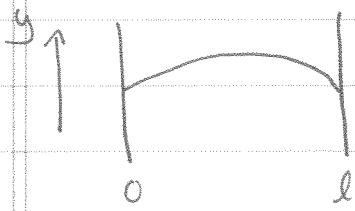
v is the speed a disturbance moves along the string

$\frac{\partial}{\partial x}$ is a partial derivative, so the CWE is called a partial differential equation (PDE)

$x \& t$ are independent variables

y is a dependent variable

If the string is stretched between 2 walls:



$y(0,t) = 0$ } These are boundary
 $y(l,t) = 0$ } conditions.

The CWE tells us that there's a relationship between acceleration ($\frac{\partial^2 y}{\partial t^2}$) and curvature ($\frac{\partial^2 y}{\partial x^2}$)

$$\frac{\partial^2 y(x,t)}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 y(x,t)}{\partial t^2}$$



This is the "rulebook" for wave motion, much like F=ma is the "rulebook" for particle motion.

If we want to know how a particular string behaves we need to solve this differential equation.

Separating the variables

The first trick we'll use is "separation of variables"

$$y(x,t) = X(x) T(t)$$

which makes the assumption that we can factor out the spatial ($X(x)$) behavior from the time-dependent $T(t)$ part:

We do this because the factored fractions sail right through partial derivatives. Here's an example

$$T(t) = t+4$$

$$X(x) = x^2 + 2x + 3$$

$$\begin{aligned} \text{Assume: } y(x,t) &= X(x) T(t) = (x^2 + 2x + 3)(t+4) \\ &= x^2 t + 2x t + 3t + 4x^2 + 8x + 12 \end{aligned}$$

Now, let's consider what happens under a partial derivative:

$$y(x,t) = x^2t + 2xt + 3t + 4x^2 + 8x + 12$$

$$\begin{aligned}\frac{\partial y}{\partial x} &= 2xt + 2t + 8x + 8 \\&= x(2t + 8) + 1(2t + 8) \\&= 2x(t+4) + 2(t+4) \\&= (2x+2)(t+4) \\&= \frac{\partial X(x)}{\partial x} T(t)\end{aligned}$$

$$\begin{aligned}\frac{\partial y}{\partial t} &= x^2 + 2x + 3 \\&= X(x) * 1 \\&= X(x) \frac{\partial T(t)}{\partial t}\end{aligned}$$

So, when we have partial derivatives, we can separate variables to factor out time & spatial dependence into separate equations:

$$y(x,t) = X(x) T(t)$$

$$\begin{aligned}\frac{\partial^2 y}{\partial x^2} &= \frac{\partial}{\partial x} \left(\frac{\partial y}{\partial x} \right) = \frac{\partial}{\partial x} \left[\frac{\partial}{\partial x} X(x) T(t) \right] = \frac{\partial}{\partial x} \left[T(t) \frac{\partial X(x)}{\partial x} \right] \\&= T(t) \frac{\partial^2 X(x)}{\partial x^2}\end{aligned}$$

Likewise:

$$\begin{aligned}\frac{\partial^2 y}{\partial t^2} &= \frac{\partial}{\partial t} \left(\frac{\partial y}{\partial t} \right) = \frac{\partial}{\partial t} \left[\frac{\partial}{\partial t} X(x) T(t) \right] = \frac{\partial}{\partial t} \left[X(x) \frac{\partial^2 T(t)}{\partial t^2} \right] \\&= X(x) \frac{\partial^2 T(t)}{\partial t^2}\end{aligned}$$

So, applying this to the Classical Wave Equation, we get:

$$T(t) \frac{\partial^2 X(x)}{\partial x^2} = \frac{1}{v^2} X(x) \frac{\partial^2 T(t)}{\partial t^2}$$

 It looks like we just made it worse!

But now we can divide both sides by the whole function $y(x, t) = X(x)T(t)$

$$\frac{1}{X(x)} \frac{d^2 X(x)}{dx^2} = \frac{1}{v^2} \frac{1}{T(t)} \frac{d^2 T(t)}{dt^2}$$

contains all of the x-dependence contains all of the t-dependence

The most subtle & hardest to understand part is this:

This separated form must be true for all values of x and for all times t. The only way for that to be true is if both sides are constant.

$$\frac{1}{X(x)} \frac{d^2 X(x)}{dx^2} = -k \quad k \text{ is called a separation constant}$$

$$\frac{1}{v^2 T(t)} \frac{d^2 T(t)}{dt^2} = -k \quad \text{It is negative by convention.}$$

We can re write these as:

$$\frac{d^2 X(x)}{dx^2} + k X(x) = 0$$

$$\frac{d^2 T(t)}{dt^2} + k v^2 T(t) = 0$$

Two ordinary
2nd order
differential
equations that
are linked by
k.

Now, to solve these, guess

$$X(x) = e^{\alpha x}$$

(19)

$$\frac{d}{dx} e^{\alpha x} = \alpha e^{\alpha x} = \alpha X(x)$$

$$\frac{d^2}{dx^2} e^{\alpha x} = \alpha^2 e^{\alpha x} = \alpha^2 X(x)$$

$$\alpha^2 X(x) + k X(x) = 0$$

$$(\alpha^2 + k) X(x) = 0$$

\downarrow $X(x) = 0$ is called the "trivial" solution

$\alpha^2 + k = 0$ gives us the solution we want

$$\alpha^2 = -k$$

$$\alpha = \pm \sqrt{-k} = \pm \sqrt{-1} \sqrt{k}$$

$$\alpha = \pm i\sqrt{k} \quad \leftarrow \text{2 complex roots}$$

$$X(x) = e^{\pm i\sqrt{k}x} \quad \leftarrow \text{2 solutions}$$

$$X(x) = \frac{e^{+i\sqrt{k}x} + e^{-i\sqrt{k}x}}{2} = \cos(\sqrt{k}x) \quad \text{is also a solution}$$

$$X(x) = \frac{e^{i\sqrt{k}x} - e^{-i\sqrt{k}x}}{2i} = \sin(\sqrt{k}x) \quad \text{is also a solution}$$

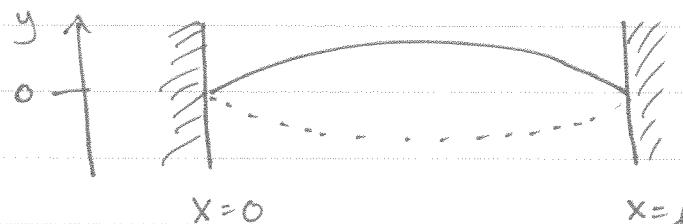
Generally:

$$X(x) = A \cos(\sqrt{k}x) + B \sin(\sqrt{k}x)$$

These are called the general solutions to the spatial part of the wave equation. A & B are still unknown numbers at this point.

To find them, we need to use the boundary conditions:

Boundary conditions:



$$\left. \begin{array}{l} y(0, t) = 0 \\ y(l, t) = 0 \end{array} \right\} \text{fixed boundaries}$$

This boundary condition tells us that we can't have any $\cos(x)$ contribution because $\cos(0) = 1$, so we know that $A = 0$.

$$\therefore X(x) = B \sin(\sqrt{k} x)$$

$\underbrace{}_{1}$ $\underbrace{\phantom{\sin(\sqrt{k} x)}}_{2}$

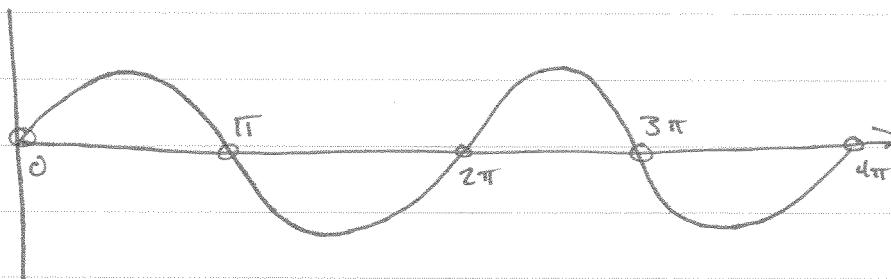
2 unknowns

What about the other boundary?

$$X(l) = 0 = B \sin(\sqrt{k} l)$$

$$\therefore \sin(\sqrt{k} l) = 0$$

The \sin function only has zeroes at specific values: $x = n\pi \rightarrow \sin(x) = 0$ n is the integers



\therefore to satisfy the other boundary condition, $x = n\pi$

$$\sqrt{k} l = n\pi$$

$$\sqrt{k} = \frac{n\pi}{l} \quad \rightarrow \quad k = \frac{n^2 \pi^2}{l^2}$$

So now we only have 1 unknown:

$$X(x) = B \sin\left(\frac{n\pi x}{l}\right)$$

← This function satisfies both boundary conditions for any value of n that is an integer

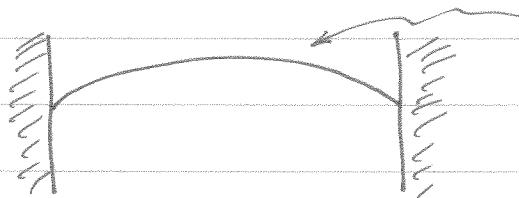
Now, on to time dependence:

$$\frac{d^2 T(t)}{dt^2} + k v^2 T(t) = 0 \quad \text{remember that } \sqrt{k} = \frac{n\pi}{l}$$

This is a very similar equation to the spatial ($X(x)$) equation, so a similar solution will probably work here also.

What are the boundary conditions on $T(t)$?

If we pull a string that we release when $t=0$



stationary at $t=0$

$$\frac{dy(x,t)}{dt} = 0 \quad \text{at } t=0 \quad \text{for all } x$$

$$\therefore \frac{dT(t)}{dt} = 0 \quad \text{at } t=0$$

$$\frac{d^2 T(t)}{dt^2} + \underbrace{\frac{n^2 \pi^2}{l^2} v^2}_{\text{!!}} T(t) = 0$$

ω_n^2 on each value of n gives a different const.

$$T(t) = e^{\alpha t}$$

$$(\alpha^2 + \omega_n^2) T(t) = 0 \quad \rightarrow \alpha^2 = -\omega_n^2$$

$$\alpha = \pm i \omega_n$$

Last time:

$$\text{CWE: } \frac{\partial^2 y(x,t)}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 y(x,t)}{\partial t^2}$$



The "rules" containing all the physics ($F=ma$)

Separation of variables:

$$y(x,t) = X(x)T(t)$$

\hookrightarrow y is what happens to an actual & particular String

$$\frac{d^2 X(x)}{dx^2} + k X(x) = 0 \quad \begin{array}{l} \text{separate} \\ \text{2nd order} \\ \text{differential eqs.} \end{array}$$

$$\frac{d^2 T(t)}{dt^2} + k v^2 T(t) = 0$$

Solution for $X(x)$:

$$X(x) = A \cos(\sqrt{k'} x) + B \sin(\sqrt{k'} x)$$

$$\text{Apply boundaries: } X(0) = 0 \rightarrow A = 0$$

$$X(l) = 0 \rightarrow \sqrt{k'} l = n\pi$$

$$\sqrt{k'} = \frac{n\pi}{l}$$

$$\therefore X(x) = B \sin\left(\frac{n\pi}{l} x\right)$$

Now, on to time dependence (remember that $\sqrt{k'} = \frac{n\pi}{l}$)

$$\frac{d^2 T(t)}{dt^2} + k v^2 T(t) = 0$$

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$$\frac{d^2 T(t)}{dt^2} + \underbrace{\frac{n^2 \pi^2 V^2}{l^2}}_{\omega_n^2} T(t) = 0$$

$$\omega_n = \frac{n \pi V}{l}$$

To solve this we assume $T(t) = e^{\alpha t}$

$$\hookrightarrow T' = \alpha e^{\alpha t} \rightarrow T'' = \alpha^2 e^{\alpha t}$$

$$\begin{aligned}\alpha^2 T(t) + \omega_n^2 T(t) &= 0 \\ (\alpha^2 + \omega_n^2) T(t) &= 0\end{aligned}$$

$$\alpha^2 + \omega_n^2 = 0$$

$$\alpha^2 = -\omega_n^2$$

$$\alpha = \pm \sqrt{-1} \sqrt{\omega_n^2}$$

$$\alpha = \pm i \omega_n$$

$\therefore T(t) = e^{i \omega_n t}$ or $e^{-i \omega_n t}$ or any combination of these

$$T(t) = C_1 \cos(\omega_n t) + C_2 \sin(\omega_n t)$$

Let's verify this quickly:

$$T'(t) = -\omega_n C_1 \sin(\omega_n t) + \omega_n C_2 \cos(\omega_n t)$$

$$\begin{aligned}T''(t) &= -\omega_n^2 C_1 \cos(\omega_n t) - \omega_n^2 C_2 \sin(\omega_n t) \\ &= -\omega_n^2 T(t)\end{aligned}$$

$$\therefore \frac{d^2 T(t)}{dt^2} + \omega_n^2 T(t) = -\omega_n^2 T(t) + \omega_n^2 T(t) = 0$$

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So, we've just verified that

$$T(t) = C_1 \cos(\omega_n t) + C_2 \sin(\omega_n t)$$

works in the time differential equation when $\omega_n = \frac{n\pi v}{l}$

We can put the whole thing together:

$$y_n(x,t) = \underbrace{B \sin\left(\frac{n\pi x}{l}\right)}_{X(x)} \underbrace{[C_1 \cos(\omega_n t) + C_2 \sin(\omega_n t)]}_{T(t)}$$

Combining coefficients, we get:

$$y_n(x,t) = [C_{1,n} \cos(\omega_n t) + C_{2,n} \sin(\omega_n t)] \sin\left(\frac{n\pi x}{l}\right)$$

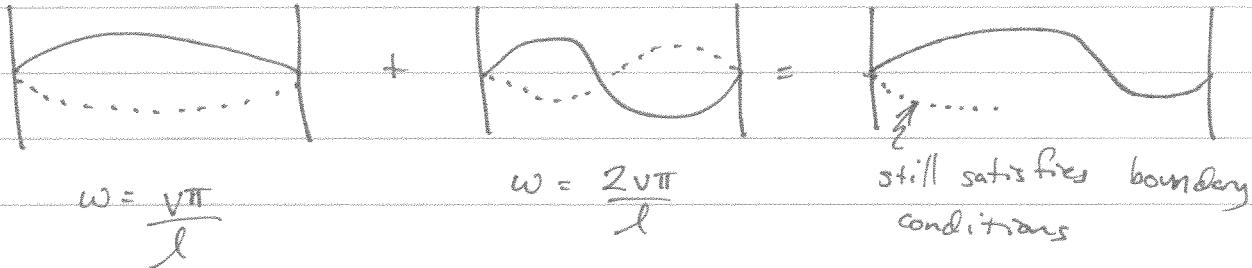
where $n = 1, 2, 3, \dots$

and $\omega_n = \frac{n\pi v}{l}$

This gives us an infinite series of possible solutions. The $n=1$ solution is called the fundamental. Higher n solutions are called "harmonics".

<u>Math</u>	<u>ω_n</u>	<u>MUSIC</u>	<u>Note</u>
$n=1$	$v\pi/l$	fundamental 1 st or 0 th harmonic	C
$n=2$	$2v\pi/l$	1 st overtone or 2 nd harmonic	C (octave)
$n=3$	$3v\pi/l$	2 nd overtone	G (major 5 th)
$n=4$	$4v\pi/l$		C (2 octaves)
$n=5$	$5v\pi/l$		E (major 3 rd)

Real sounds (and wavefunctions) are combinations, or hybrids of these harmonics



$$y(x,t) = [F_1 \cos(\omega_1 t) + G_1 \sin(\omega_1 t)] \sin \frac{\pi x}{l} + [F_2 \cos(\omega_2 t) + G_2 \sin(\omega_2 t)] \sin \frac{2\pi x}{l}$$

Most generally:

$$y(x,t) = \sum_{n=1}^{\infty} [F_n \cos \omega_n t + G_n \sin \omega_n t] \sin \frac{n\pi x}{l}$$

We can always rewrite sums of $\sin + \cos$ with the same argument in a simpler form. This is a problem on problem set 2.

$$y(x,t) = \sum_{n=1}^{\infty} A_n \cos(\omega_n t + \phi_n) \sin \left(\frac{n\pi x}{l} \right)$$

↑ ↑ ↑ ↑
 amplitude of frequency phase of length
 mode n of mode n of mode n of string
 $\omega_n = \frac{v\pi n}{l}$ (set by initial conditions)

And that's the solution to the classical wave equation in 1-D. We've left some things out

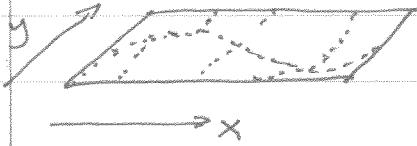
- 1) Friction (Damps the string at long times)
- 2) Bowing (forcing the string into an oscillation)
- 3) "Fretting" touching the string at a nodal point

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In 2 dimensions

Membranes or drumheads vibrating between clamped edges.

$u(x, y, t)$ = height of membrane
at position (x, y) and
time t



$$\frac{\partial^2 u(x, y, t)}{\partial x^2} + \frac{\partial^2 u(x, y, t)}{\partial y^2} = \frac{1}{v^2} \frac{\partial^2 u(x, y, t)}{\partial t^2}$$

This is the classical wave equation in 2D.
How do we solve it?

First, separation of variables:

$$u(x, y, t) = X(x) Y(y) T(t)$$

why?

$$\frac{\partial^2 u}{\partial x^2} = Y(y) T(t) \frac{\partial^2 X(x)}{\partial x^2}$$

$$\frac{\partial^2 u}{\partial y^2} = X(x) T(t) \frac{\partial^2 Y(y)}{\partial y^2}$$

$$\frac{\partial^2 u}{\partial t^2} = X(x) Y(y) \frac{\partial^2 T(t)}{\partial t^2}$$

← partial derivatives
only act on one of the functions

In the CWE, these become:

$$Y(y) T(t) \frac{\partial^2 X(x)}{\partial x^2} + X(x) T(t) \frac{\partial^2 Y(y)}{\partial y^2} = \frac{1}{v^2} X(x) Y(y) \frac{\partial^2 T(t)}{\partial t^2}$$

divide by $u = X(x) Y(y) T(t)$

$$\frac{1}{X(x)} \frac{\partial^2 X(x)}{\partial x^2} + \frac{1}{Y(y)} \frac{\partial^2 Y(y)}{\partial y^2} = \frac{1}{v^2 T(t)} \frac{\partial^2 T(t)}{\partial t^2}$$

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$$\underbrace{\frac{1}{X(x)} \frac{\partial^2 X(x)}{\partial x^2}}_{\text{all } x} + \underbrace{\frac{1}{Y(y)} \frac{\partial^2 Y(y)}{\partial y^2}}_{\text{all } y} = \underbrace{\frac{1}{V(T(t))} \frac{\partial^2 T(t)}{\partial t^2}}_{\text{all } t}$$

|| || ||

$$-p^2 + -q^2 = -s^2$$

\nearrow three constants

Leads to 3 diff eqs:

$$\frac{d^2 X(x)}{dx^2} + p^2 X(x) = 0$$

$$\frac{d^2 Y(y)}{dy^2} + q^2 Y(y) = 0$$

$$\frac{d^2 T(t)}{dt^2} + V_s^2 s^2 T(t) = 0$$

All are nearly identical to the 1D
2nd order

Differential equations

General solutions

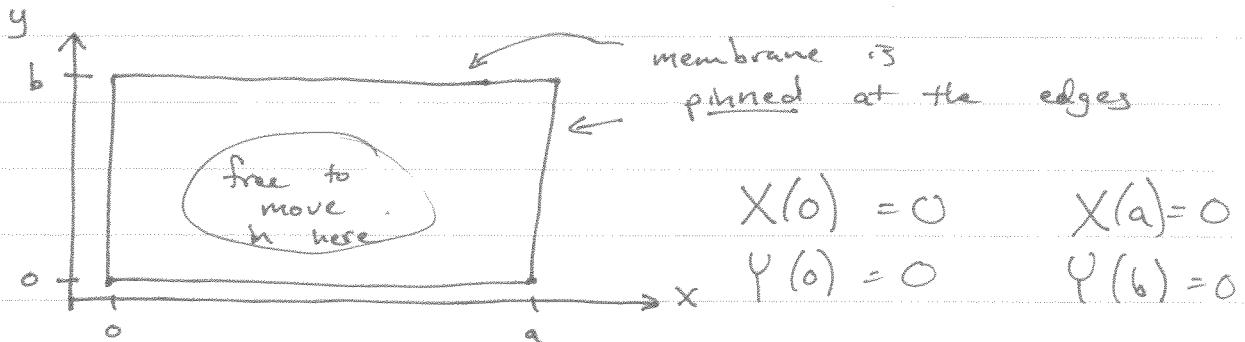
$$X(x) = A \cos(px) + B \sin(px)$$

$$Y(y) = C \cos(qy) + D \sin(qy)$$

$$T(t) = E \cos(vst) + F \sin(vst)$$

Boundary conditions in 2D:

for a rectangular membrane



$$\begin{aligned} X(0) &= 0 & X(a) &= 0 \\ Y(0) &= 0 & Y(b) &= 0 \end{aligned}$$

$$\therefore X(x) = B \sin\left(\frac{n\pi x}{a}\right) \quad p = \frac{n\pi}{a}$$

$$Y(y) = D \sin\left(\frac{m\pi y}{b}\right) \quad q = \frac{m\pi}{b}$$

n & m are both integers

$$\begin{aligned} n &= 1, 2, 3, \dots \\ m &= 1, 2, 3, \dots \end{aligned}$$

We also know

$$\begin{aligned} p^2 + q^2 &= s^2 \\ \frac{n^2\pi^2}{a^2} + \frac{m^2\pi^2}{b^2} &= s^2 = \frac{\omega_{nm}^2}{V^2} \end{aligned}$$

you're going to
define ω_{nm}
in terms of
 n & m :

$$\omega_{nm}^2 = V^2 \pi^2 \left(\frac{n^2}{a^2} + \frac{m^2}{b^2} \right)$$

$$\omega_{nm} = V\pi \sqrt{\frac{n^2}{a^2} + \frac{m^2}{b^2}}$$

$$u(x, y, t) = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} A_{nm} (\cos \omega_{nm} t + \phi_{nm}) \sin\left(\frac{n\pi x}{a}\right) \sin\left(\frac{m\pi y}{b}\right)$$

Amplitude frequency phase
 ω_{nm}

$$\omega_{nm} = V\pi \sqrt{\frac{n^2}{a^2} + \frac{m^2}{b^2}}$$

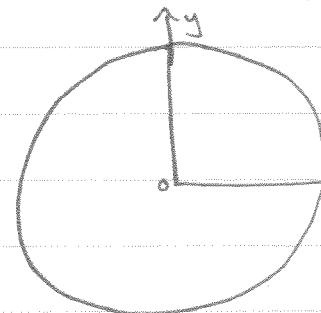
For a square membrane

$$\omega_{nm} = \frac{V\pi}{a} \sqrt{n^2 + m^2}$$

$\therefore \omega_{21} = \omega_{12} = \text{doubly degenerate}$

(frequencies of 2 modes are the same)

What happens for non-rectangular boundaries



$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{1}{v^2} \frac{\partial^2 u}{\partial t^2}$$

{ This is still the rule book

↳ boundary conditions are not as amenable to simple solution.

In this case we have to replace

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \rightarrow \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}$$

$$\frac{\partial^2 u(r, \theta)}{\partial r^2} + \frac{1}{r} \frac{\partial u(r, \theta)}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u(r, \theta)}{\partial \theta^2} = \frac{1}{v^2} \frac{\partial^2 u(r, \theta, t)}{\partial t^2}$$

{ The same classical wave equation, but recast in cylindrical coordinates.